

### 3.2 ‘Controlling by Thought? – Brain Computer Interfaces and Embedded Brain Reading – An Introduction’ (II-T-02)

*Elsa Andrea Kirchner*<sup>(1) (2)</sup>

*(1) Universität Bremen, Arbeitsgruppe Robotik, Robert-Hooke-Straße 1, 28359 Bremen, Germany*

*(2) DFKI GmbH, Robotics Innovation Center, Robert-Hooke-Straße 1, 28359 Bremen, Germany*

Contact: [elsa.kirchner@dfki.de](mailto:elsa.kirchner@dfki.de)

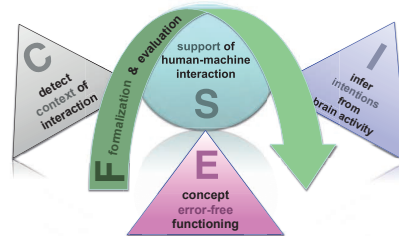
#### Abstract

Machines, like PCs or robots, can be controlled by brain signals. Brain activity is often used to reestablish communication and control for human that are disabled to move or to communicate. Brain computer interfaces, which are used to link the human brain with a machine, do often require the attention of the human to enable explicit control. For such approaches it is unimportant how and which brain signal is used. Highest relevance has robustness and easiness. Using brain activity for the support of healthy people brings new challenges. Adding the link between brain and machine must not require extra cognitive resources from the human. Thus, for many applications a rather passive approach that uses brain activity implicitly should be chosen. However, beside the question on how to use brain activity, i.e., implicitly or explicitly, other questions are also relevant for the development of intelligent and intuitive interfaces for control or support. For example, other technical or physiological data can improve reliability but bring along challenges for signal processing and classification and must be handled by adequate software frameworks.



## Controlling by Thought? Brain Computer Interfaces and Embedded Brain Reading – An Introduction

Project Day Work Group  
Interaction & ROCON  
Dr. Elsa A. Kirchner  
Robotics Lab, University of Bremen and  
DFKI RIC



### What Kind of Interface? BCI: Brain-Computer Interface



- A brain computer interface (BCI) is classically used to control a machine or PC:

„ A BCI is a direct link or interface between brain and PC that recognizes certain patterns in the brains activity that are translated into signals for communication and control.“ (adapted from Wolpaw et al. 2002)



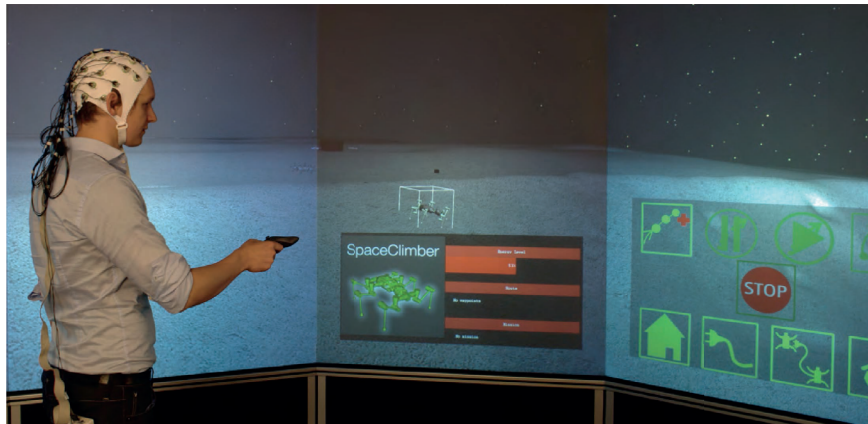
### What Kind of Interface? MonsterMind BCI



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### What Kind of Interface? Passive Support



- e.g., adaptation of an MMI with respect to mental workload
  - can be based on behavioral data (missing of responses, response time etc.) or
  - **biosignals**



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## What Kind of Interface?

## Biosignals versus Psychophysiological Data



- **Biosignal:** a signal that is caused by a biological system or subsystem, i.e., by its biological activity
  - biological system: e.g., a human or ... a bacteria
  - subsystem: e.g., the humans brain, skin, muscles, eyes....
- A biosignal can be interpreted to tell us something about the biological system,
  - e.g., its behavior or state, and can thus be a **psychophysiological** measure.
  - It can be used for affective computing, for e.g. gaming, that incorporates real-time software **adaption** to the psychophysiological activity of the user
- Biosignals can be used to **control a machine**,
  - e.g., by eye movement or brain signals in classic brain computer interfaces (BCIs)

## Psychophysiological Data

## Active Control and Passive Adaptation



psychophysiological data\* can be applied for:

\*like muscle activity, pulse, brain activity...

active control

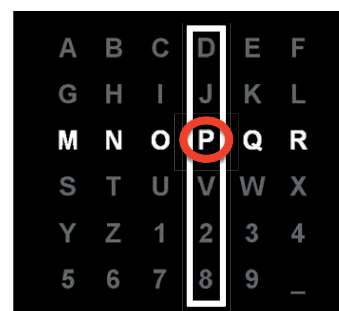
passive adaptation

brain activity is used for:

P300 Speller  
(Farwell and Donchin, 1988)

active  
brain-computer interfaces (BCI)<sup>1</sup>

explicit  
information transfer



<sup>1</sup>Farwell and Donchin, 1988; Pfurtscheller, 2000; Wolpaw et al., 2002; Allison et al., 2007

<sup>2</sup>Pope et al., 1995; Allanson and Fairclough, 2004

<sup>3</sup>Blankertz et al., 2002; Zander et al., 2009; Haufe et al., 2011

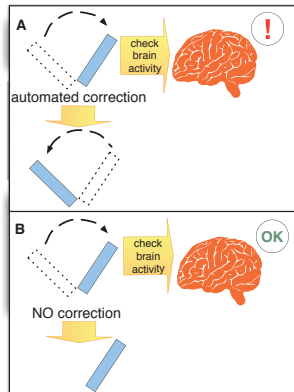
[https://kaggle2.blob.core.windows.net/competitions/kaggle/4043/media/P300\\_Speller.mp4](https://kaggle2.blob.core.windows.net/competitions/kaggle/4043/media/P300_Speller.mp4)

Psychophysiological Data  
 Active Control and Passive Adaptation



psychophysiological data\* can be applied for:

\*like muscle activity, pulse, brain activity...



passive adaptation

biocybernetic adaptation<sup>2</sup>  
 passive BCIs<sup>3</sup>

implicit information transfer

error-detection  
 (Blankertz et al., 2002)

<sup>1</sup>Farwell and Donchin, 1988; Pfurtscheller, 2000; Wolpaw et al., 2002; Allison et al., 2007

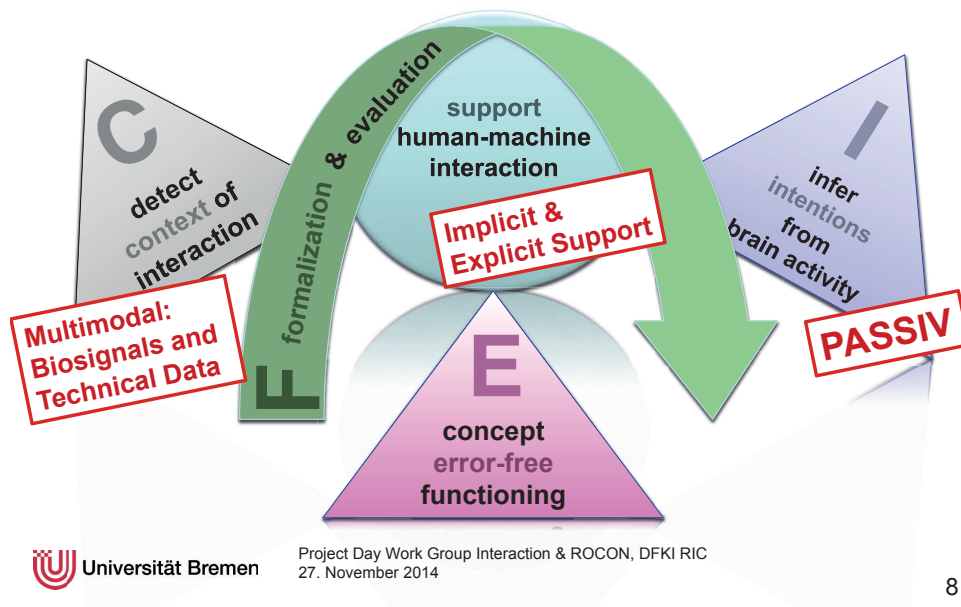
<sup>2</sup>Pope et al., 1995; Allanson and Fairclough, 2004

<sup>3</sup>Blankertz et al., 2002; Zander et al., 2009; Haufe et al., 2011 [https://kaopie2.blob.core.windows.net/competitions/kaopie/4043/media/P300\\_Speller.mpd](https://kaopie2.blob.core.windows.net/competitions/kaopie/4043/media/P300_Speller.mpd)



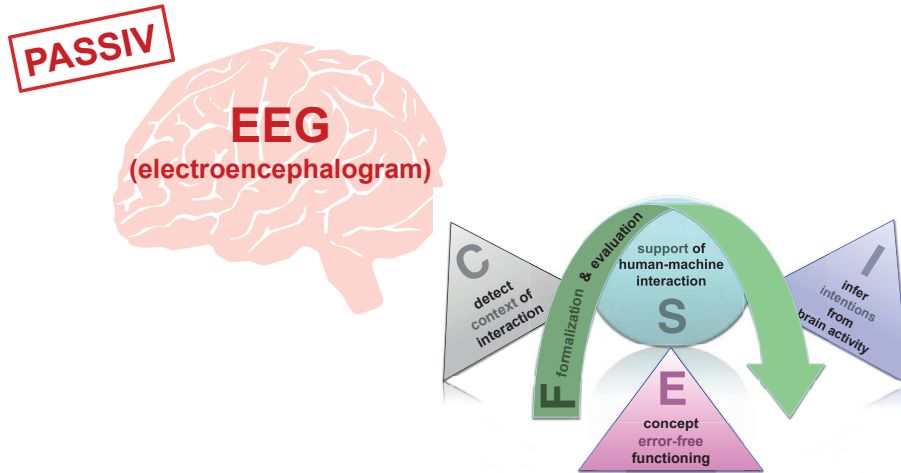
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Concept  
 Embedded Brain Reading



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Concept  
Embedded Brain Reading



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Theoretical Background  
The Human Electroencephalogram (EEG)



EEG

raw signals

**Pros:**

- recorded **non-invasively**
- high temporal resolution
- cheap recording devices

**Cons:**

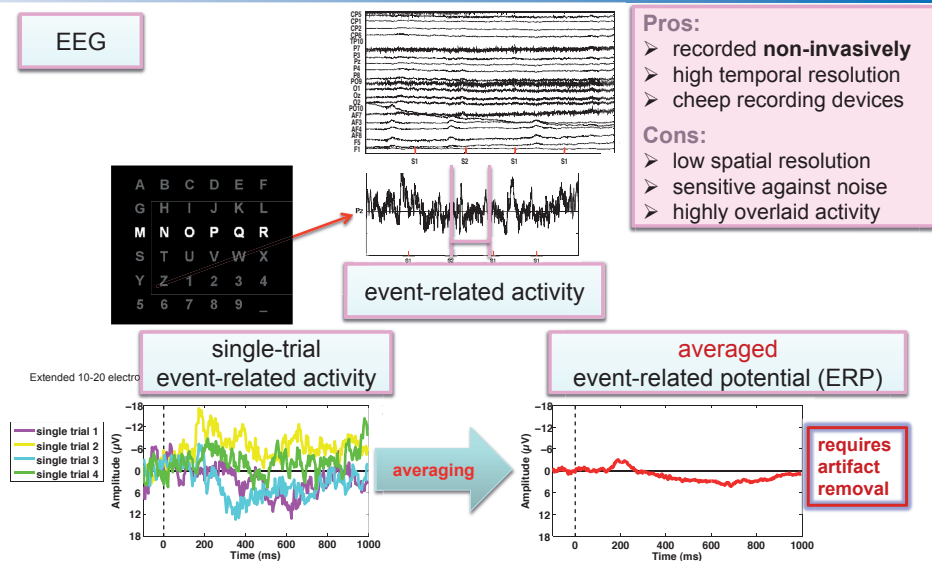
- low spatial resolution
- sensitive against noise
- highly overlaid activity

Extended 10-20 electrode system (Society, 1991).

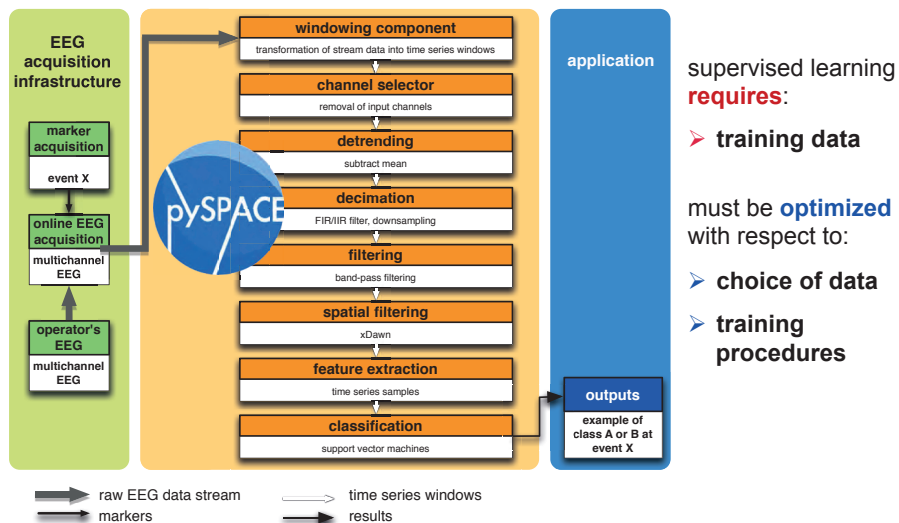


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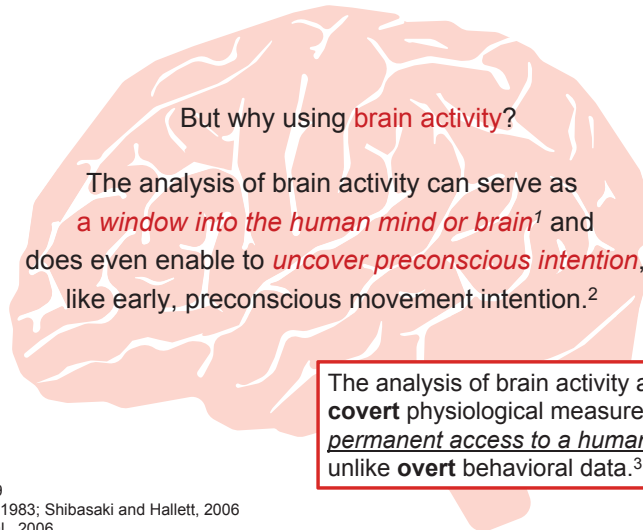
## Theoretical Background The Human Electroencephalogram (EEG)



## pySPACE Single-Trial EEG Analysis



Concept  
Why Using EEG Data?



But why using **brain activity**?

The analysis of brain activity can serve as **a window into the human mind or brain**<sup>1</sup> and does even enable to **uncover preconscious intention**, like early, preconscious movement intention.<sup>2</sup>

The analysis of brain activity as a **covert** physiological measure enables **permanent access to a human's state** unlike **overt** behavioral data.<sup>3</sup>

<sup>1</sup>Coles, 1989

<sup>2</sup>Libet et al., 1983; Shibasaki and Hallett, 2006

<sup>3</sup>Gerson et al., 2006



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Embedded Brain Reading  
Applications



**Thank You for Your Attention!**

**EEG**

- movement preparation detection
- possible movement trigger

**EMG**

- physical movement detection
- confirmation of esp. based movement prediction
- movement system prediction
- possible movement trigger in later rehabilitation phase

**Eye-tracking**

- prediction of users' desires
- movement path activation
- possible movement trigger in very early establishment phase after brain lesion

**Exoskeleton**

- user assistance / control
- movement planning (3D, 2D, 1D)
- active movement execution
- force feedback application

**Virtual scenario**

- full virtual immersion
- visual feedback
- force feedback application
- energetic control and supervision



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